

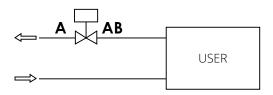


# **Smart Balancing Control Valve**

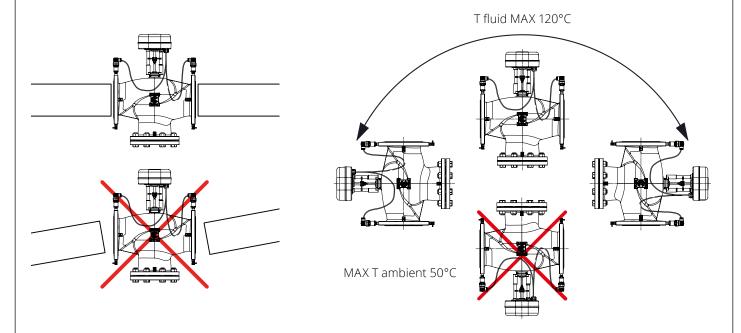
## **VALVE INSTALLATION**

## **Hydraulic Connections:**

Follow the fluid directions as shown in the diagram below.



Before installing the valve, make sure the pipes are clean and free from weld slag in order not to damage the internal parts of the valve itself.



Before the valve start-up, check if the flow correspond to the indication printed on the valve body. The valve has the following specification according to stem position:

- Stem down = fluid passing
- Stem up = fluid intercepted

#### **OPERATING CONDITIONS**

Temperature, nominal pressure and differential pressure on the valve must be within the values specified in data sheets EBV\_DBL603en.

## PIPE FLUSHING

An anomalous valve leackage is caused, in almost all cases, by weld slag or foreign bodies entrapped between the valve seat and the plug, often causing damages.

To prevent such inconveniences, it is advisable to use filters upstream of the valve.

Moreover, the pipelines must be properly washed positioning the valve stem at half stroke; this operation must be performed before start-up and after a prolonged shutdown of the system.

The performances stated in this sheet can be modified without any prior notice.

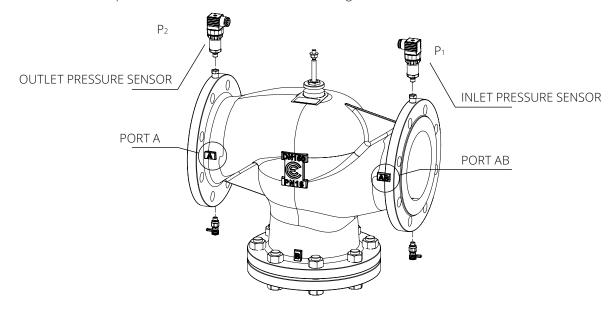


## **VALVE MAINTENANCE**

Valves are equipped with a stuffing box with a double Oring and, therefore, they do not require any particular maintenance. In case of irregular leakage, O-Rings and stem packing have to be replaced.

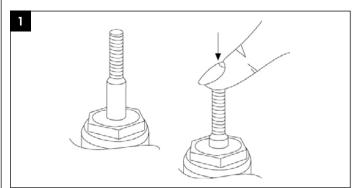
## PRESSURE SENSORS INSTALLATION

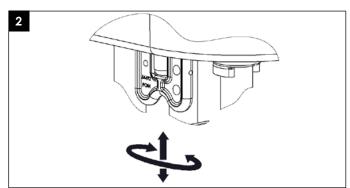
Make sure that the fluid is not present in the system and remove the closing caps on the valve flanges. Insert the MF extension and pressure transducers as indicated in the figure below.

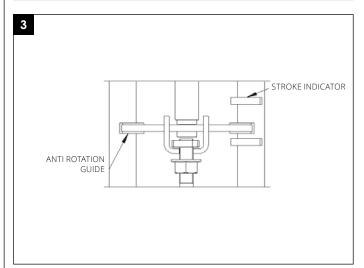


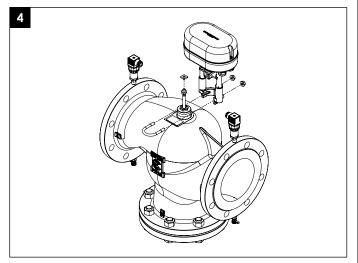
## **ACTUATOR INSTALLATION**

The actuators must not be installed in explosive atmosphere and must not be subjected to steam jets of water or dripping. Leave a space above the actuator sufficient to allow the uncoupling of the actuator from the valve body for any maintenance, at least 10-15 cm.









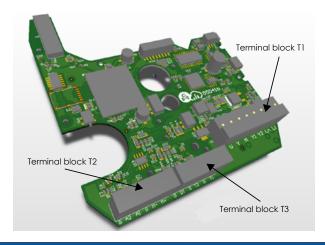
## WIRING CONNECTION

Remove the cover screw with a screwdriver and then remove the cover as shown in the picture beside.

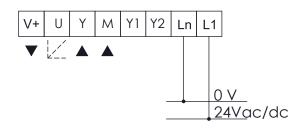
The actuator is equipped with 3 removable terminal blocks:

- a removable 8-pole terminal block (T1) with power supply, analog and digital command signal and feedback signal;
- a removable 6-pole terminal block (T2) dedicated to the RS-485 bus connection (Modbus);
- a removable 6-pole terminal block (T3) dedicated to the connections of the temperature sensors (only 4 poles are used).





## **TERMINAL BLOCK T1**

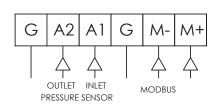






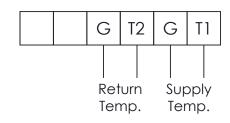
Label	Description	Function	Cable type	Max wire length			
L1	24Vac/dc	Dower cupply	AWG 16 (min 1mm² - max	75 m			
Ln	0V	Power supply	1,5mm²)				
Υ	0-10Vdc	Modulating control input	AWG 20 (min 0,5mm <sup>2</sup> -	200 m			
М	0V (common)	Modulating control input	max 1,5mm²)				
Y1		Note	usad				
Y2	Not used						
V+	16Vdc	Power supply for pressure	AWG 20 (min 0,5mm <sup>2</sup> -	200 m			
М	0V (common)	sensors	max 1,5mm²)				
U	2-10Vdc	Foodback output signal	AWG 20 (min 0,5mm <sup>2</sup> -	200			
М	0V (common)	Feedback output signal	max 1,5mm²)	200 m			

## **TERMINAL BLOCK T2**



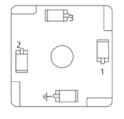
Label	Description	Function	Cable type	Max wire length	
M+	Tx			See chapter Modbus – RS485	
M-	Rx	Modbus connection	Belden 8762		
G	Shield				
A1	0-10 V from pressure sensor (inlet pressure)	ADroading		75 cm	
A2	0-10 V from pressure sensor (outlet pressure)	ΔP reading	Three-core cable supplied		
G	0 V (Common)	Pressure sensor common		75 cm	

## TERMINAL BLOCK T3



Label	Description	Function	Max wire length	
T1	Supply temp. sensor			
G	Common	ΔT limit function, energy monito-	3 m	
T2	Return temp. sensor	ring and power control function	3 111	
G	Common			

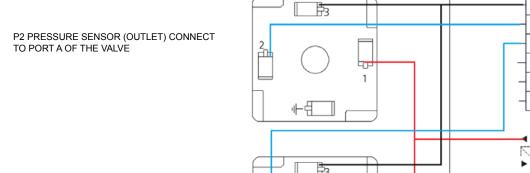
# PRESSURE TRANSDUCERS CONNECTION



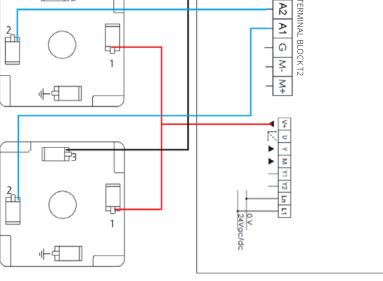
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DIN CONNECTOR EN175301-803-A

Label	Description	Function	Cable type	Max wire length	
1	Power supply				
2	0-10V Signal	Differential Pressure Reading	Three poles wire (sup- plied)	75 cm	
3	Common	reduing			

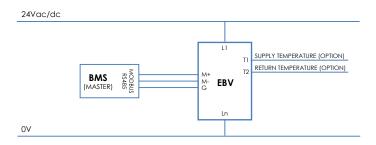


P1 PRESSURE SENSOR (INLET) CONNECT TO PORT AB OF THE VALVE

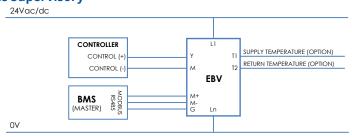


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#### **Modbus Control**



## **Modulanting Control & Modbus Supervisory**



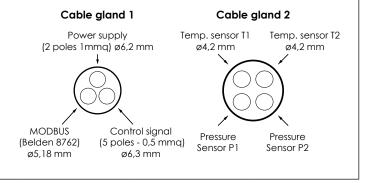
**Note:** To avoid damages to electronic components caused by the PCB bending, do not press too much while fixing the terminal block.

Each pole of the terminal blocks is clearly marked and the same label is on the electronic board.
Before turning on the actuator make sure that the terminal blocks are correctly connected to the board and that the labels on the terminals and board match.

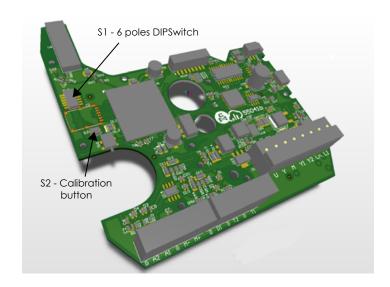
## **CABLE GLAND**

The actuator is supplied with 2 cable glands with punched membranes for safe and tidy wiring.

- Cable gland 1 for 3 cables: 2-wire cable for power supply;
   5-wire cable for control and feedback signals and 3-wire cable for Modbus;
- Cable gland 2 for 4 cables: 2 cables with 2 wires for temperature sensors (if present) and 2 cables with 3 wires for pressure trasmitters.



# DIPSWITCH SETTING



DIP switch	OFF	ON			
	Direct action	Reverse action			
1	U = 2V U = 10V	U = 10V U = feedback U = 2V			
2	Modulating Control (MOD) (Input between Y [+] and M [-])	Not used			
3	Normal operating	Firmware update			
4	Modulating Control 0-10Vdc (DIP n. 2 OFF only)	Modulating Control 2-10Vdc (DIP n. 2 OFF only)			
5	Not used	Not used			
6	Voltage Input Signal (input between Y [+] and M [-])	Current Input Signal 4-20mA (input between Y [+] and M [-])			

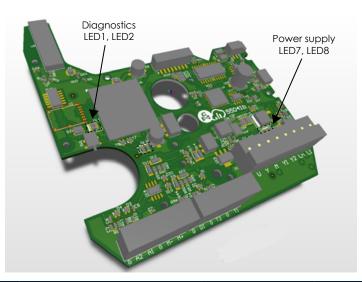
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#### **DIAGNOSTIC - ALARM FUNCTIONS** Actuator Restore proce-N° Error type Actuator behavior LEDs notification Possible anomaly status dure The actuator returns to its Calibration / initial position and does not Remove power Stroke less Valve with stroke respond to the command. The **RED ON** and re-power first than 5 mm less than 5 mm installation actuator keeps the previous again stroke or the default stroke The actuator leaves the ma-1 ximum range of 60mm and moves to the new extreme. Valve with stroke Calibration / Remove power Stroke Once the new stroke limit is greater than 60 RED fast blinking + greater than first and re-power reached, it returns to the initial **GREEN ON** mm or incorrect 60 mm installation again position signaling an anomaly. coupling The actuator does not learn the new stroke. The actuator checks the stall condition 5 times. At the end of Unexpected the attempts it signals an anocollision Normal Reverse the con-2 maly. The actuator does NOT RED fast blinking Valve blocked within the operation trol signal learn the new stroke, but after stroke 60s repeats the attempts to check the blocking conditions. The actuator moves to the new crash position with low spe-Stroke greater Normal Damaged valve or Reverse the con-3 ed signaling an anomaly. The RED fast blinking than expected operation incorrect coupling trol signal actuator does NOT learn the new stroke. The actuator continues to 1. Wrong sizing of operate but performance is not RED blinking altertransformer Normal guaranteed. If the low voltage nately fast (5sec) Check and restore Low supply 4 voltage operation events persist (events greater and slow (5sec) + power than 10), the actuator stops **GREEN ON** 2. Unstable power working. supply 1. Wrong sizing of The actuator continues to transformer operate but performance is not High supply Normal guaranteed. If the high voltage Check and restore 5 **RED** slow blinking voltage operation events persist (events greater power than 10), the actuator stops 2. Unstable power working. supply 1. Incorrect temperature probe connection Normal Temperature or ΔT regulation 2. Temperature 6 Temperature Check the operation loops not working. RED blinking alterprobes damaged sensors error connection and nately fast (5sec) the condition of and slow (5sec) + 3. Temperature the temperature **GREEN ON** detected outside sensor the range of use Pressure detected Pressure Pressure or ΔP regulation outside the range Normal 7 sensors Loops not working of use or probes operation error damaged

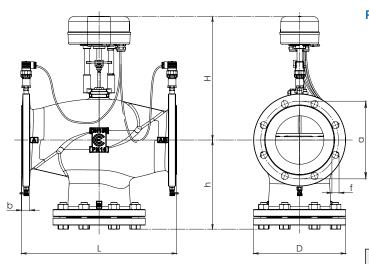
## STANDARD LEDs BEHAVIOUR

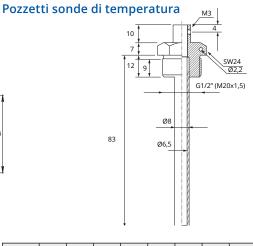
N°	LED 1 and LED 2	Actuator status		
1 FIXED GREEN Actuator has arrived at the extreme end of the calibration st				
2	2 GREEN SLOW BLINKING Actuator has arrived or is moving towards an intermediate point of the calibration stroke			
3	RED and GREEN BLINKING AL- TERNATIVELY	Actuator is calibrating the stroke or performing the initial positioning		
4	4 RED and GREEN FIXED Manual control activated, the actuator ignores the control signal. WARNIN The board is powered			

N°	N° LED 7 (RED) and LED 8 (RED) Actuator status			
1	1 LED 7 RED ON; LED 8 RED ON Stable power supply of the actuator			
2	2 LED 7 RED ON; LED 8 OFF Unstable actuator power supply; possible hardware problem			

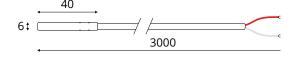


# DIMENSIONS [mm]





## Sonde di temperatura



Mod.	DN	L	Н	h	D	b	a	f	Holes	Weight [kg]
	65	290	320	175	185	20	145	18	4	18
EBV	80	310	330	186	200	22	160	18	8	28
	100	350	341	206	220	24	180	18	8	32
	125	400	364	255	250	26	210	22	8	45
	150	480	382	275	285	26	240	25	8	60

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